INTRODUCTION

Total knee arthroplasty (TKA) is a successful procedure for the majority of patients, however 20-25 percent of patients with a mechanically aligned TKA report dissatisfaction with their knee function. Correcting setting tibial component rotation is one factor that affects function. Setting component rotation is challenging because there is no consensus on the orientation of the ideal sagittal plane of the knee for establishing reference lines on the tibia, and because finding these reference lines intraoperatively is unreliable. In normal knee function, the tibia and patella flex and extend about two transverse axes perpendicular to the sagittal kinematic plane. If the goal is to restore normal knee function after TKA, then the ideal plane for setting the rotation of the tibial component is the sagittal kinematic plane. Kinematically aligned TKA is an alternative alignment method for which patient-reported satisfaction and function at 2 years is better and revisions at 3 years are fewer than mechanically aligned TKA. The goal for setting the rotation of the AP axis of the tibial component in kinematically aligned TKA is to set it parallel to the sagittal kinematic plane. Five tibial reference lines have been used in mechanically-aligned TKA to set rotation of the tibial component.

METHODS AND MATERIALS

Image analysis software was used to create a line parallel to the sagittal kinematic plane on the tibia in fifty three-dimensional (3-D) bone models of normal lower extremities from white subjects using a four-step alignment algorithm (Figure 1).

RESULTS

Eight landmarks were identified on each tibia (Figure 2).

Five tibial reference lines were drawn by connecting two landmarks and were termed (shown later in Figure 3): 1. Reference line connecting medial border of the tibial tubercle with the center of the PCL fossa. 2. Reference line connecting medial 1/3rd of the tibial tubercle with center of the PCL fossa. 3. Reference line connecting most anterior point of the tibial tubercle with center of the PCL fossa. 4. Reference line perpendicular to the line connecting the center of each tibial condyle. 5. Reference line perpendicular to the line connecting the most posterior point on each tibial condyle.

Figure 1. The composite shows a 3-D model of a right lower extremity and the four steps for orienting the extremity in the three kinematic planes.

A. The bone model was imported into software.
B. The tibia was hidden, and the femur was projected in the sagittal kinematic plane by superimposing the medial and lateral femoral condyles.
C. The femur was projected in the coronal kinematic plane and perpendicular to the sagittal kinematic plane by placing the most posterior point of each femoral condyle and greater trochanter tangent to a surface.
D. The transformations applied to the femur were applied to the tibia, the tibia was projected perpendicular to the other two planes in the axial kinematic plane, and the line parallel to the sagittal kinematic plane (yellow) was drawn on the proximal articular surface of the tibia.

The composite shows the maximum external (positive) and internal (negative) rotation of each tibial reference line (orange) from the sagittal kinematic plane (yellow). Each tibia is viewed as right. The green arc outlines the tibial tubercle. The smallest range of rotation was 22°.

Six tibial reference lines were drawn for the five tibial reference lines used in mechanically aligned TKA.

The graph shows the mean and the upper and lower 95% confidence limits (green diamond) of the rotation of each tibial reference line from the sagittal kinematic plane. The average rotation of each tibial reference line ranged from 4° to 15° external to the sagittal kinematic plane. The 95% confidence interval for all 5 tibial reference lines did not include 0°. On average none of the five tibial reference lines were parallel to the sagittal kinematic plane.

Our study shows that the five tibial reference lines common to mechanically aligned TKA externally rotate the tibial component from the sagittal kinematic plane. The surgeon can expect a wide range of component rotation when using a reference line that references the tibial tubercle because there is wide variability in the medial-lateral location of the tibial tubercle with respect to the medial border of the tibia. Accordingly, new methods that accurately set rotation of the tibial component in kinematically aligned TKA should be developed.

DISCUSSION

The present study determined whether any of these five tibial reference lines set the rotation of the tibial component parallel to the sagittal kinematic plane.